

Approximating Graph Spanners

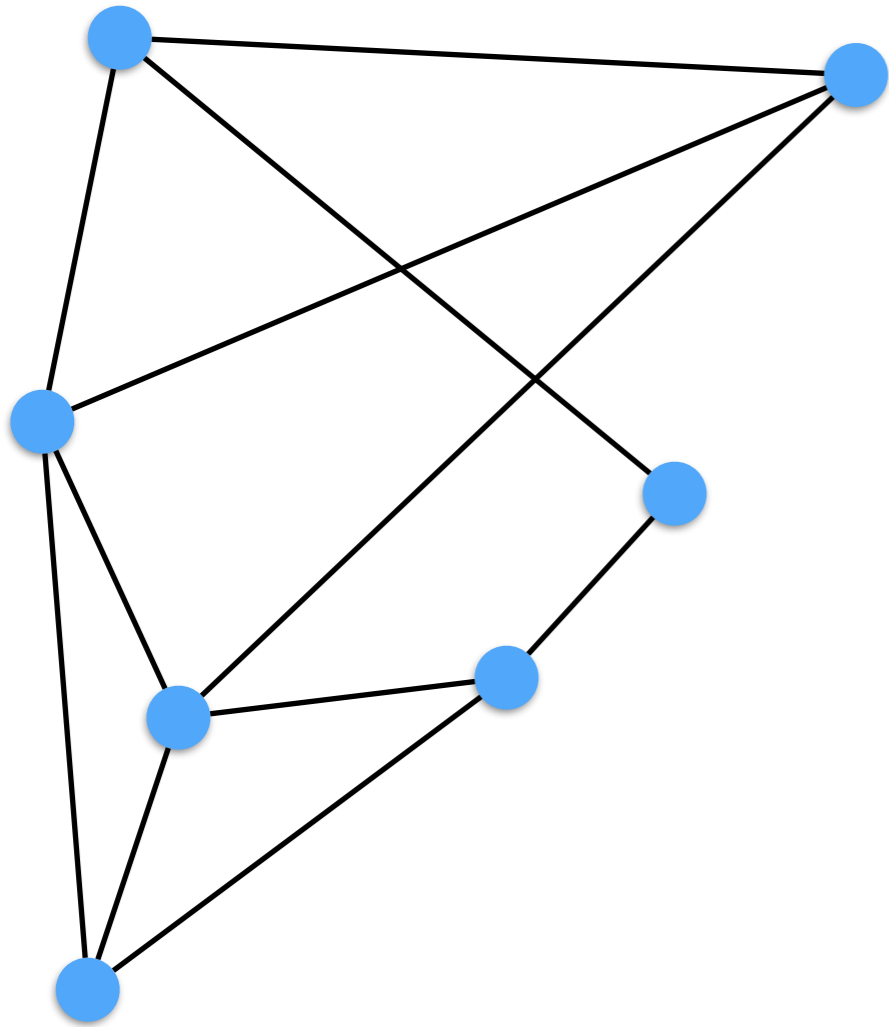
Michael Dinitz
Johns Hopkins University



Joint work with combinations of Robert Krauthgamer (Weizmann), Eden Chlamtáč (Ben Gurion), Ran Raz (Weizmann), Guy Kortsarz (Rutgers-Camden)

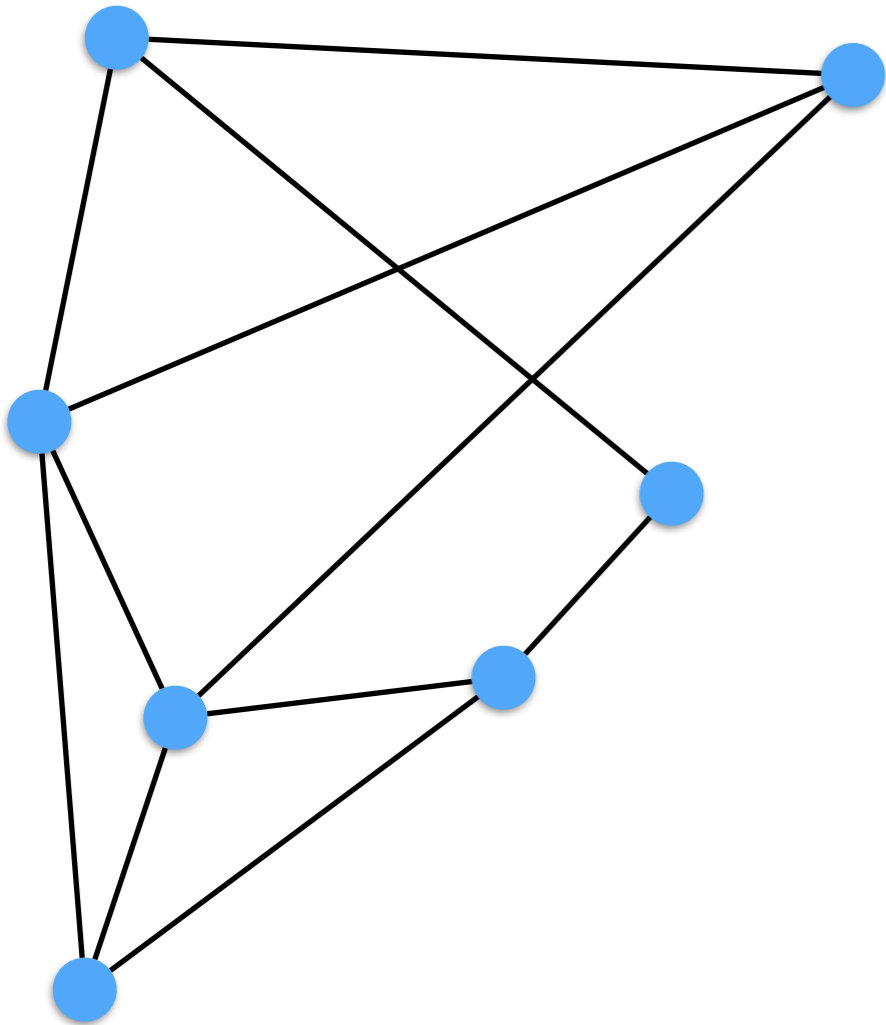
Graph Spanners

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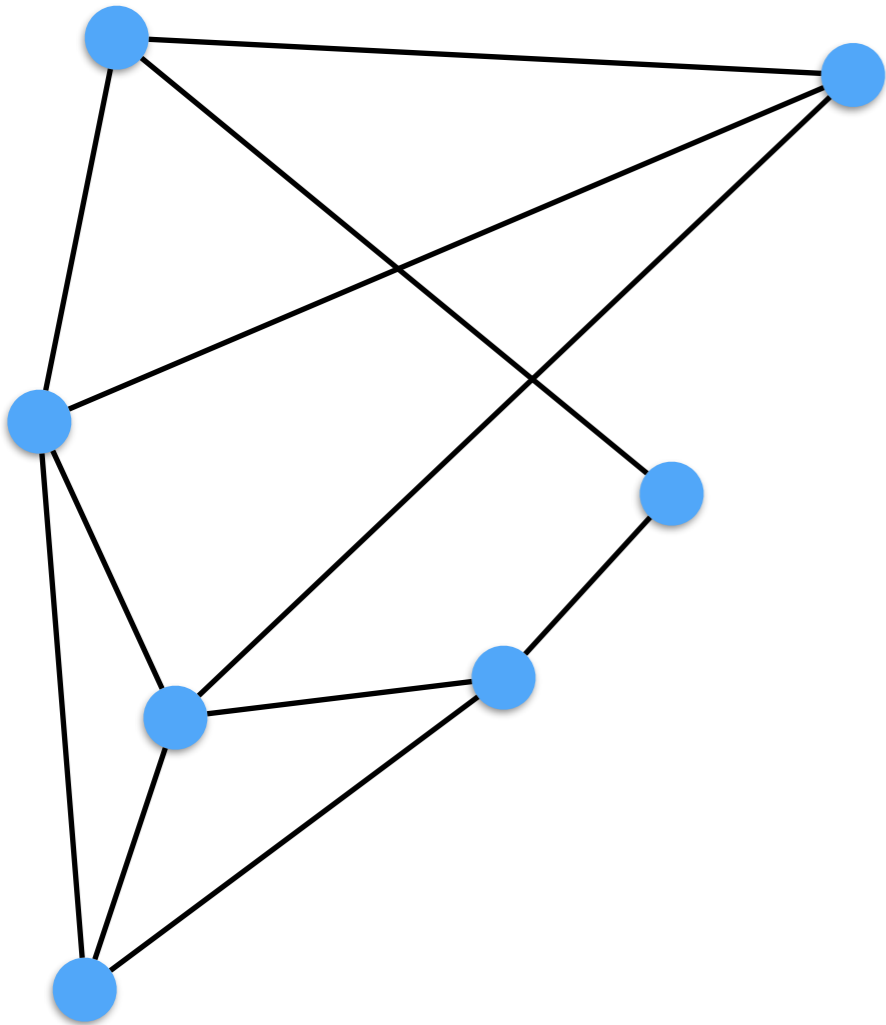
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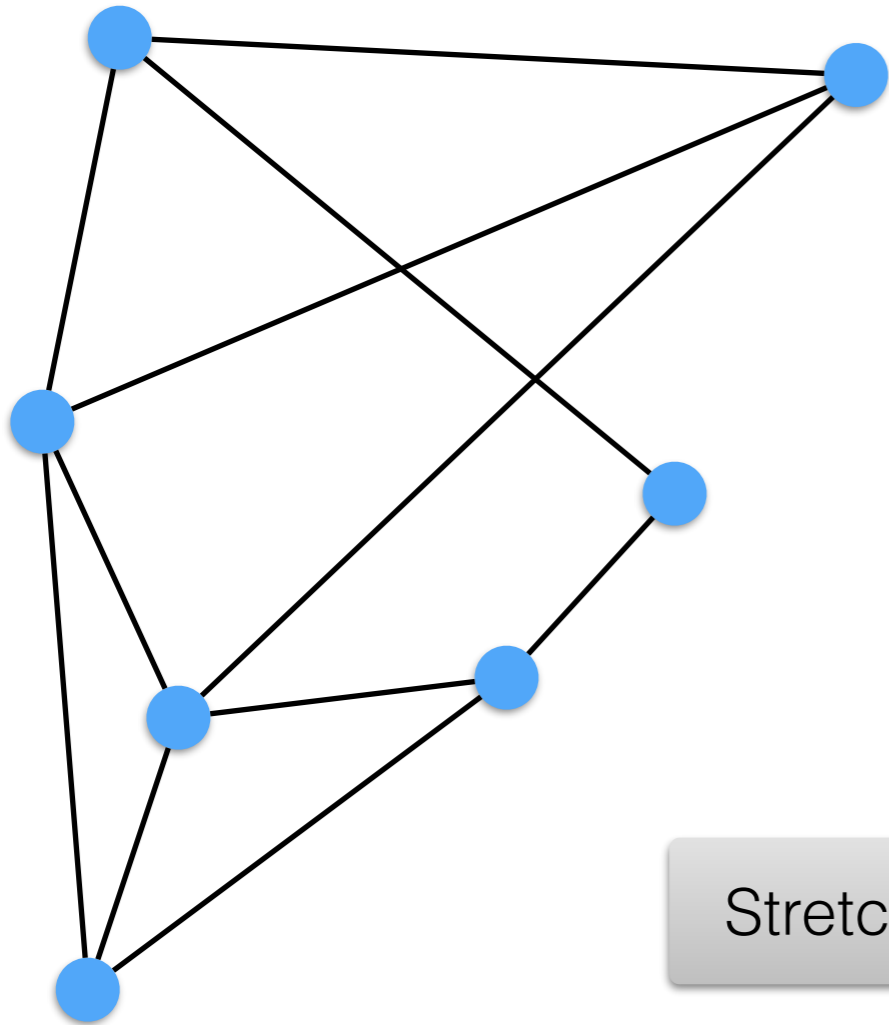


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$$d_{G'}(u, v) \leq k \times d_G(u, v)$$

for all $u, v \in V$

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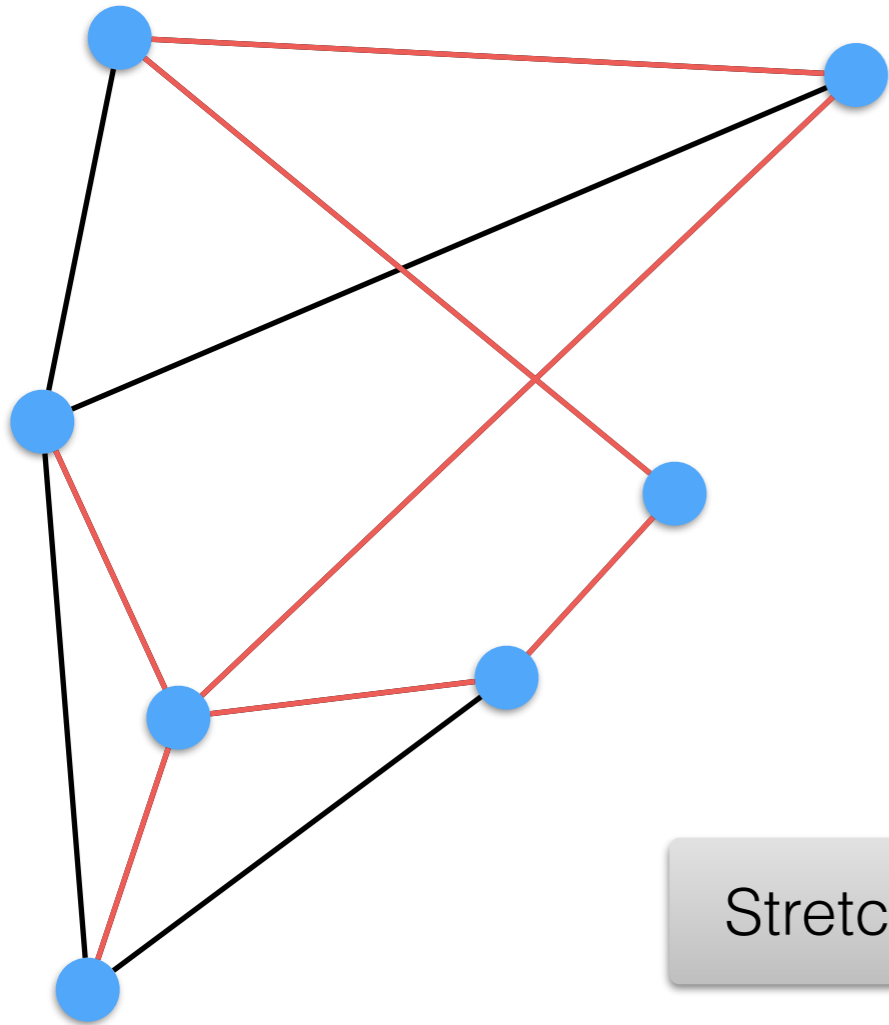


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History

- First developed in late 80's for distributed computing: Peleg-Schaffer '89, Peleg-Ullman '89
- Many applications:
 - Distance oracles / compact routing
 - Property testing
 - Preprocessing approximation algorithms
 - Maximizing influence spread in social networks
 - Biomedical image segmentation
- Many papers

Fundamental Tradeoff

Theorem [ADDJS '93]: For all $k \geq 1$, every graph G has a $(2k-1)$ -spanner with at most $n^{1+1/k}$ edges

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- Very simple greedy algorithm
- Tight (assuming Erdős girth conjecture)
- Lots of followup work extending tradeoff to weight, diameter, hop count, ... and proving stronger/different tradeoffs for special classes

What Else?

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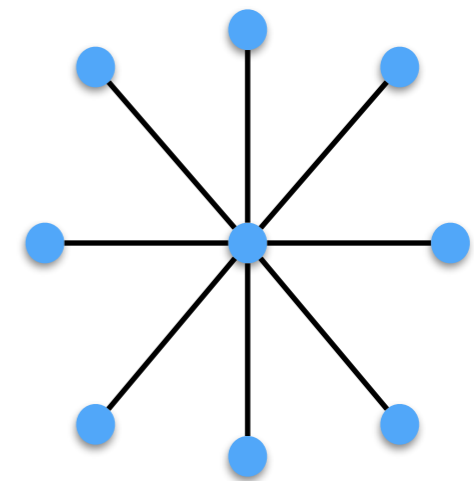
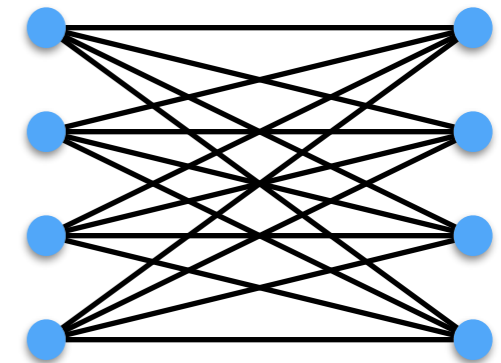
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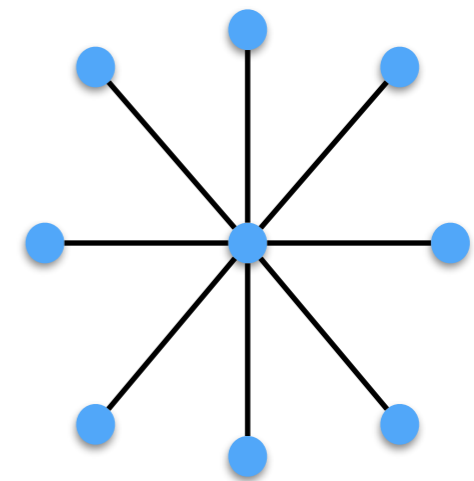
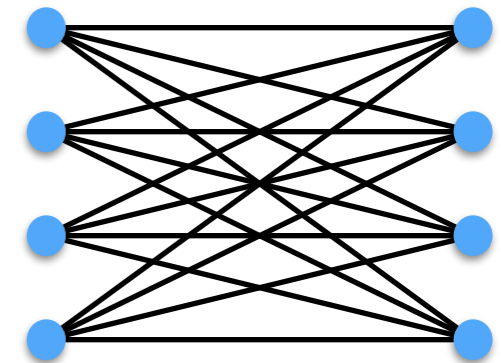
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What Else?

- Great! Tradeoff means applications using spanners can always find sparse spanners
- Not so fast....
 - Tradeoffs don't always exist (2-spanner, directed, max degree)
 - Even if they do, still want to find *best* spanner



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- “Best”:
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 - Minimum total weight
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 - ...

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 - ...
- This talk: some results, some open questions
 - Still much to do!

Basic k -Spanner

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- Most basic version: given undirected G , integer k , find k -spanner with minimum # edges

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 - $k = 2$: Tight $O(\log n)$ -approximation [Kortsarz-Peleg '92]
 - $k \geq 3$: Basic tradeoff gives $O(n^{2/(k+1)})$ -approximation (odd k) or $O(n^{2/k})$ -approximation (even k)
 - $k = 3$: $\tilde{O}(n^{1/3})$ -approximation [BBMRY '11]

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- Open Question: is it possible to beat the ADDJS bound for stretch values larger than 3?

Strong Hardness

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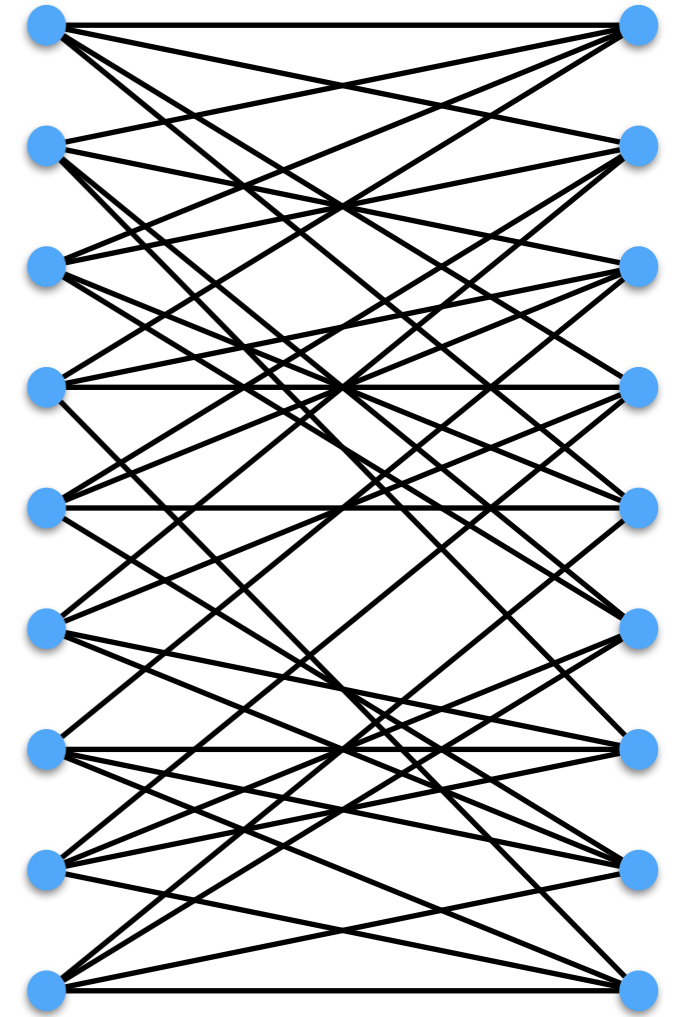
Theorem [D-Kortsarz-Raz ICALP'12]:

There is no polynomial-time algorithm that can approximate Basic k -Spanner better than $2^{(\log n)^{1-\varepsilon}} / k$ unless $NP \subseteq BPTIME(n^{\text{polylog}(n)})$

Techniques for Hardness

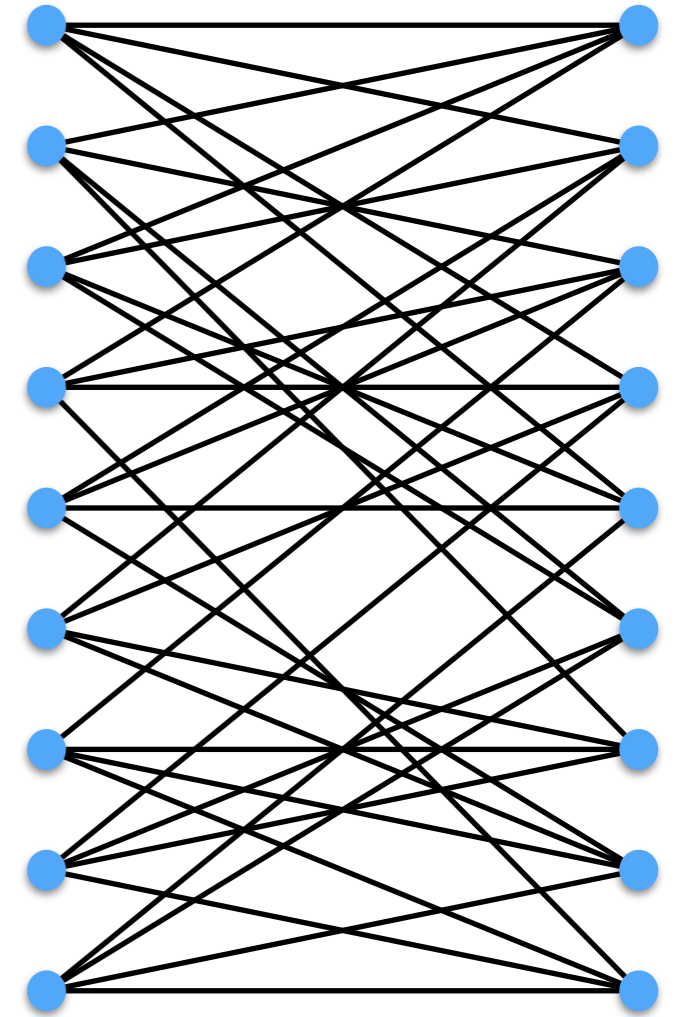
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- [Elkin-Peleg ICALP'00] framework:
Label Cover \rightarrow Label Cover with
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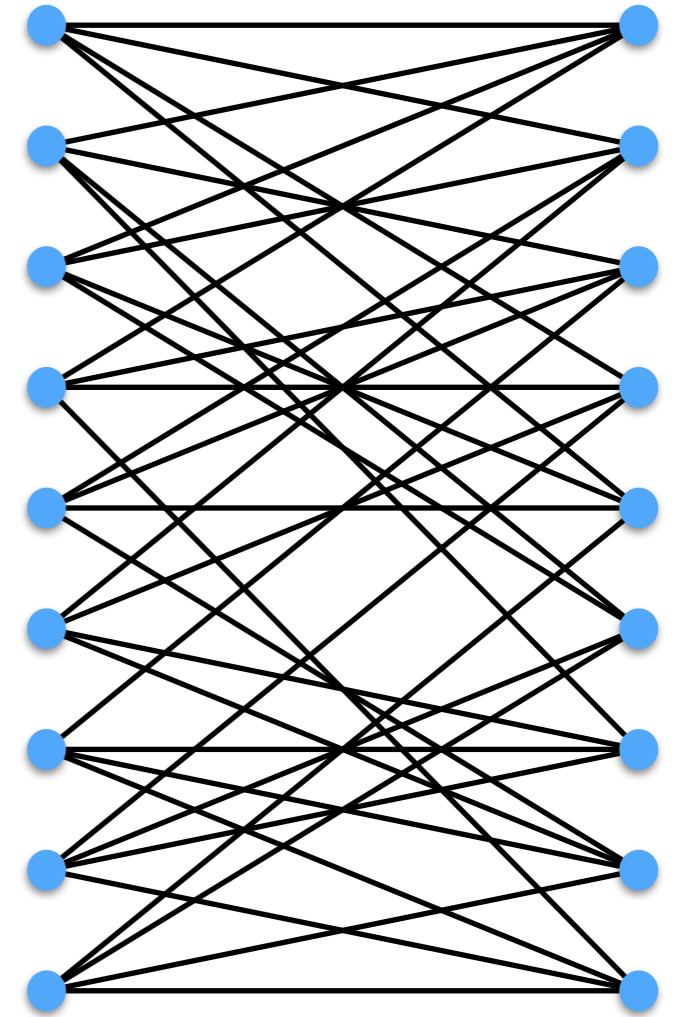
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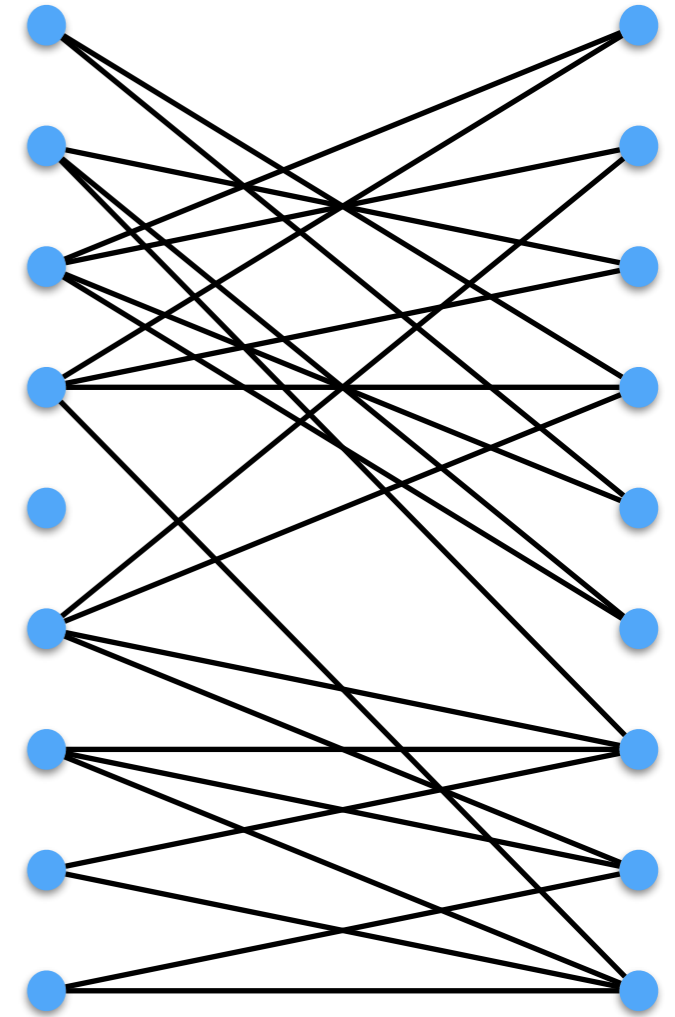
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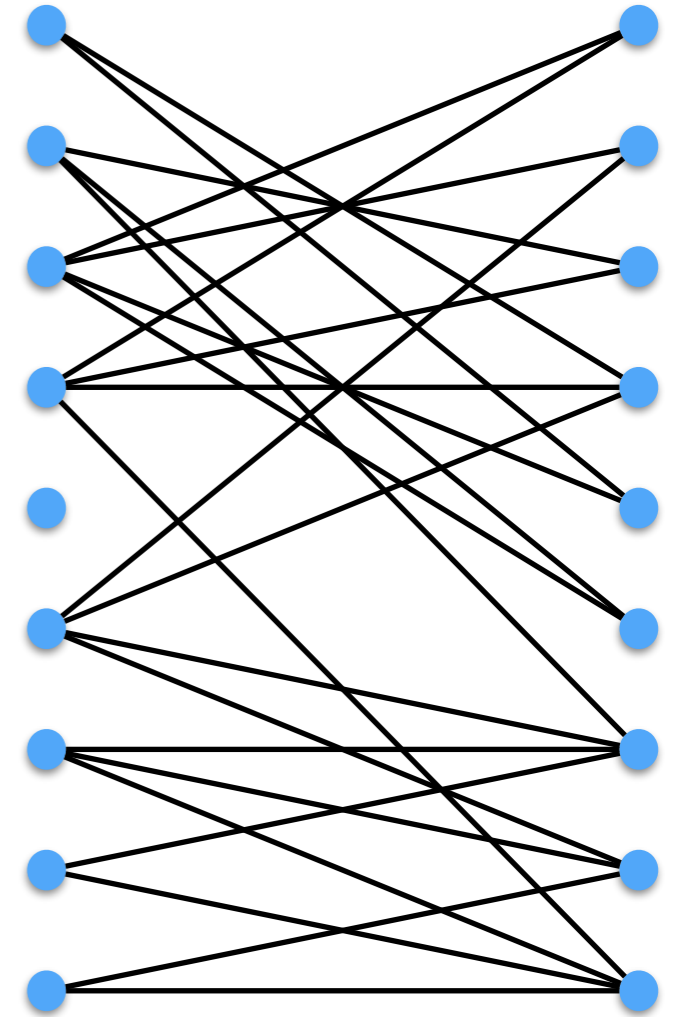
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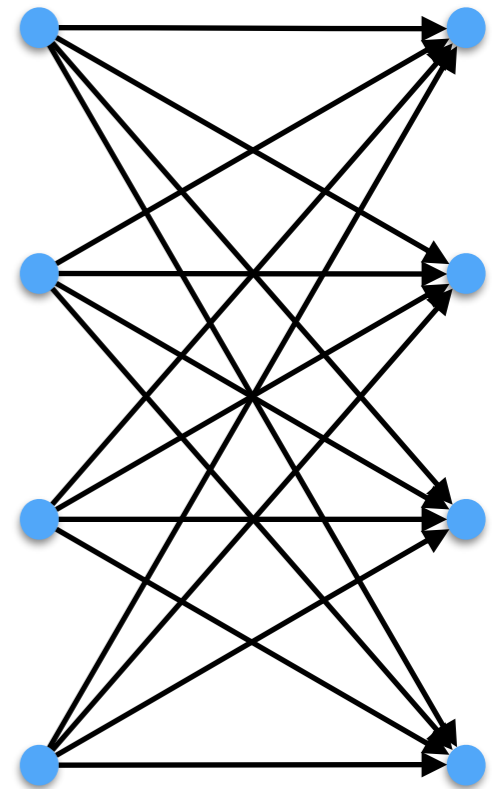
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- Second reduction straightforward:
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- Key idea: random subsampling
- Takeaway: hardness \approx degree
 - “Improvement” over parallel repetition: apply repetition, then sample
 - Same hardness, smaller degree/fewer edges



Directed Spanners

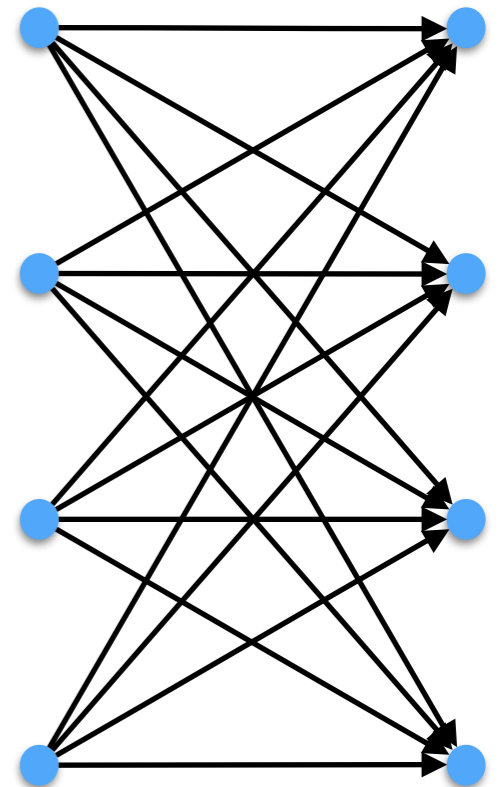
Directed Spanners

- No tradeoff possible



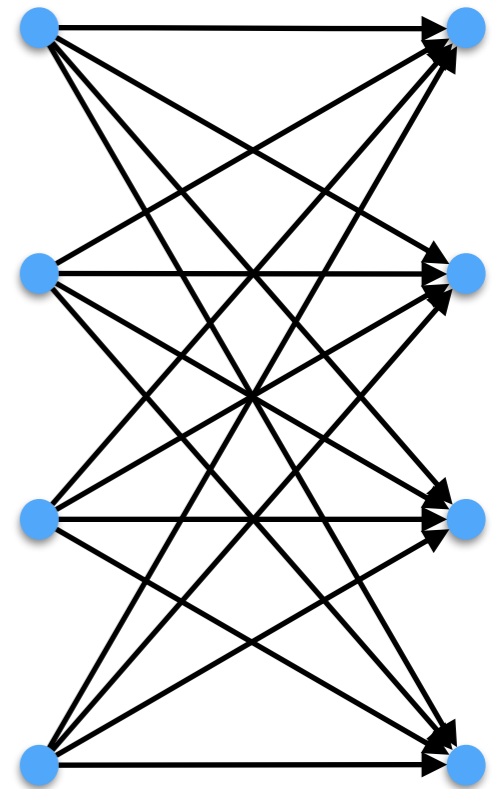
Directed Spanners

- No tradeoff possible
- Hard to approximate better than $2^{(\log n)^{(1-\epsilon)}}$
[Elkin-Peleg STACS'00]



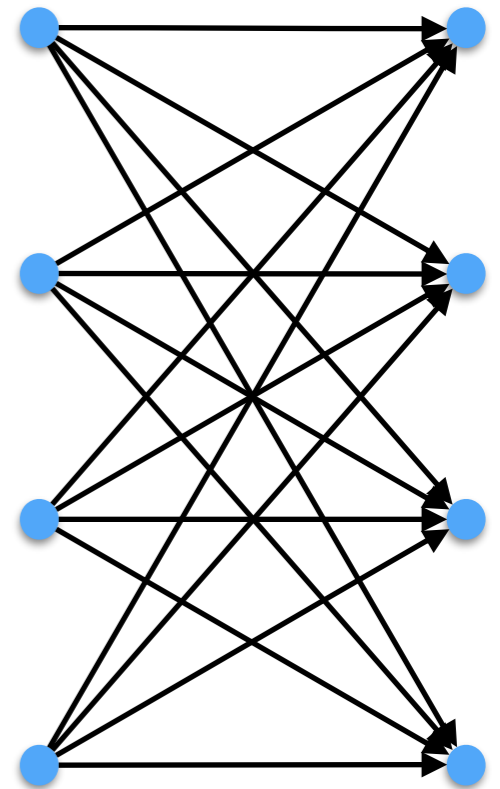
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- Upper bounds:
 - $\tilde{O}(n^{1-1/k})$ [BGJRW SODA'09]
 - $\tilde{O}(n^{2/3})$ [D-Krauthgamer STOC'11]
 - $\tilde{O}(n^{1/2})$ [BBMRY ICALP'11]

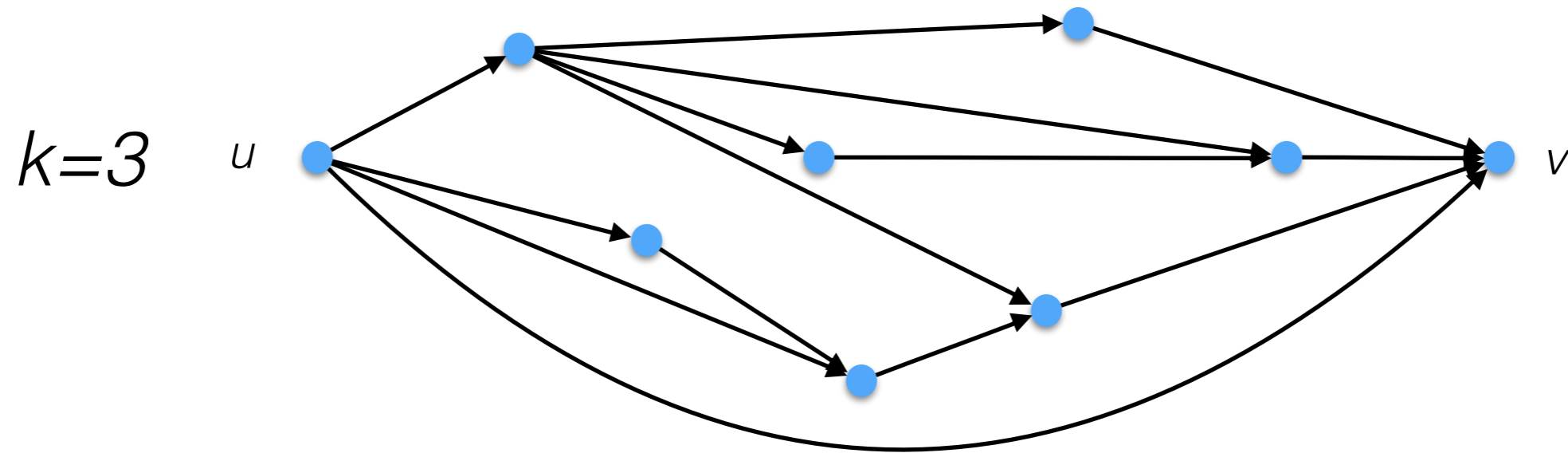


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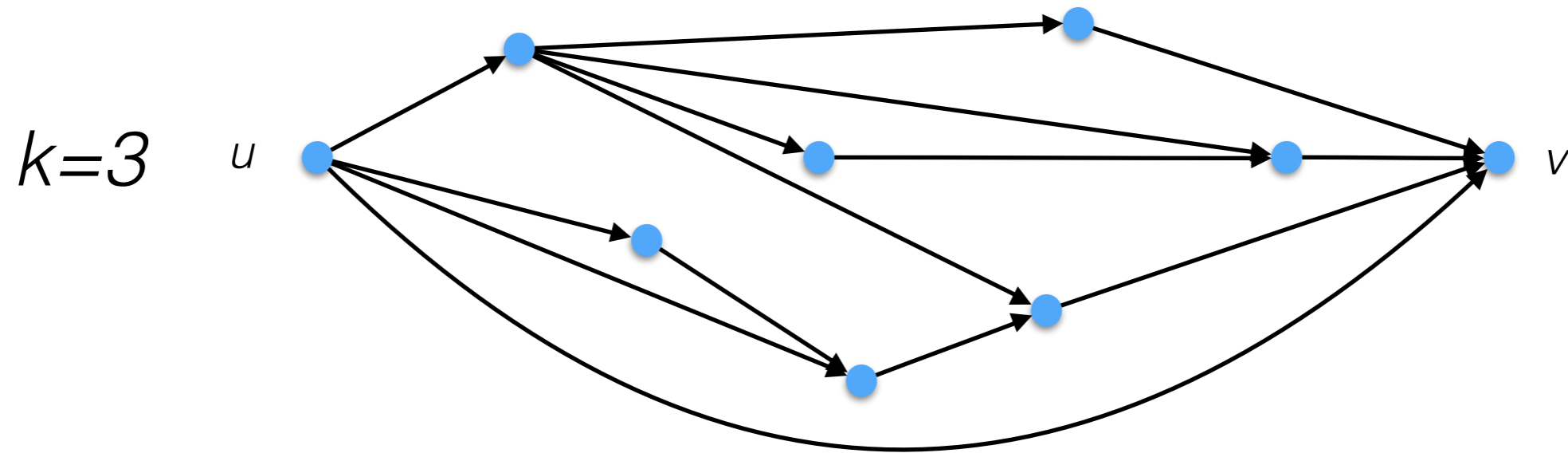
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 - Stretch 3: $\tilde{O}(n^{1/2})$ [DK STOC'11], $\tilde{O}(n^{1/3})$ [BBMRY ICALP'11]



High-Level Framework [BGJRW '09]

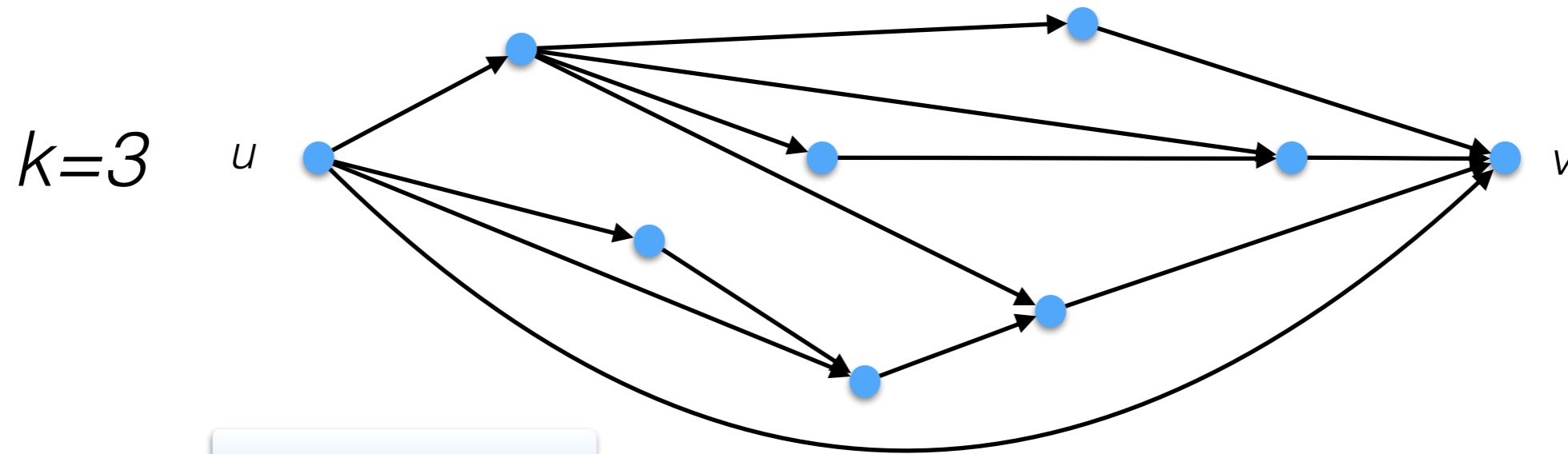


High-Level Framework [BGJRW '09]



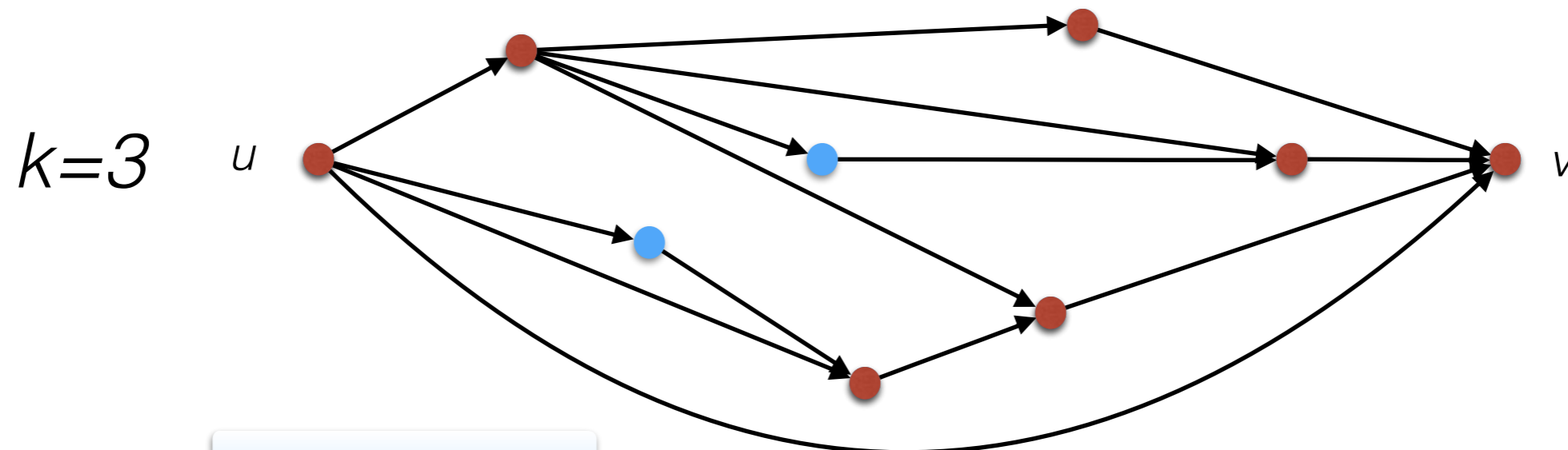
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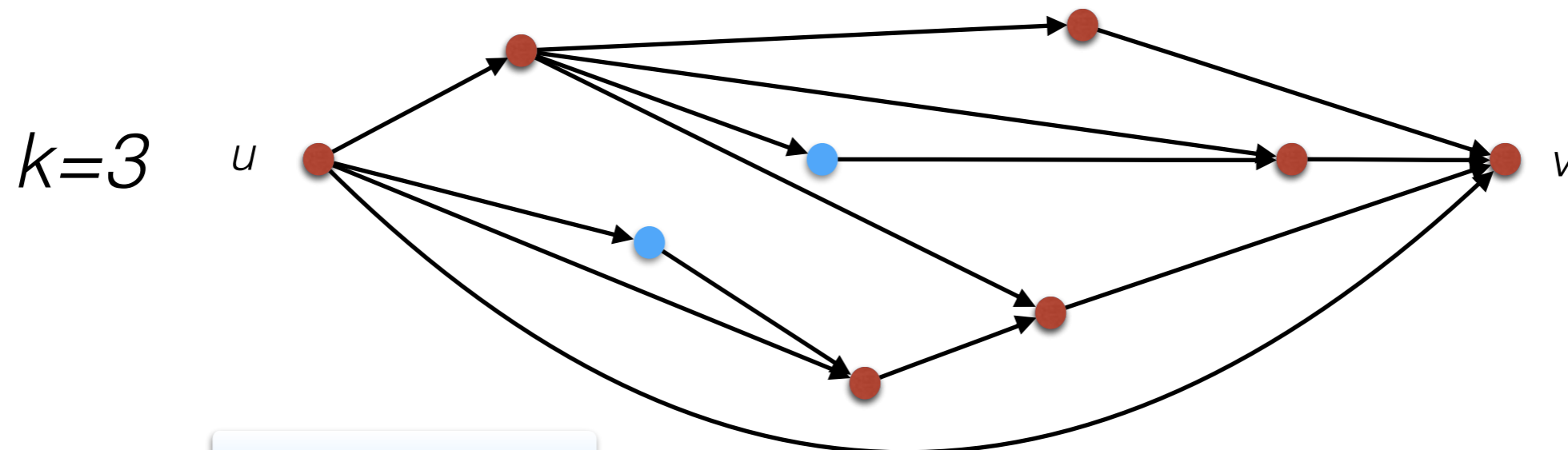
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Local
Neighborhood

- $N(u,v) = \{w : \exists \text{ stretch-}k \text{ } u\text{-}v \text{ path containing } w\}$

High-Level Framework [BGJRW '09]



- $N(u,v) = \{w : \exists \text{ stretch-}k \text{ } u\text{-}v \text{ path containing } w\}$
- Two algorithms: one for small $|N(u,v)|$, one for large

Small $|N(u,v)|$

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- Linear Program [DK '11]:

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$$\begin{array}{ll} \min & \sum_{e \in E} x_e \\ \text{s.t.} & \sum_{P \in \mathcal{P}_{u,v}: e \in P} f_P \leq x_e \quad \forall (u,v) \in E, \forall e \in E \\ & \sum_{P \in \mathcal{P}_{u,v}} f_P \geq 1 \quad \forall (u,v) \in E \\ & x_e \geq 0 \quad \forall e \in E \\ & f_P \geq 0 \quad \forall (u,v) \in E, \forall P \in \mathcal{P}_{u,v} \end{array}$$

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Stretch k u - v
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- Take e with probability t^*x_e [BBRMY '11]: spans all (u,v) where $|N(u,v)| \leq t$
 - Analysis: union over all “cuts”

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- Improves over threshold rounding [DK '11]

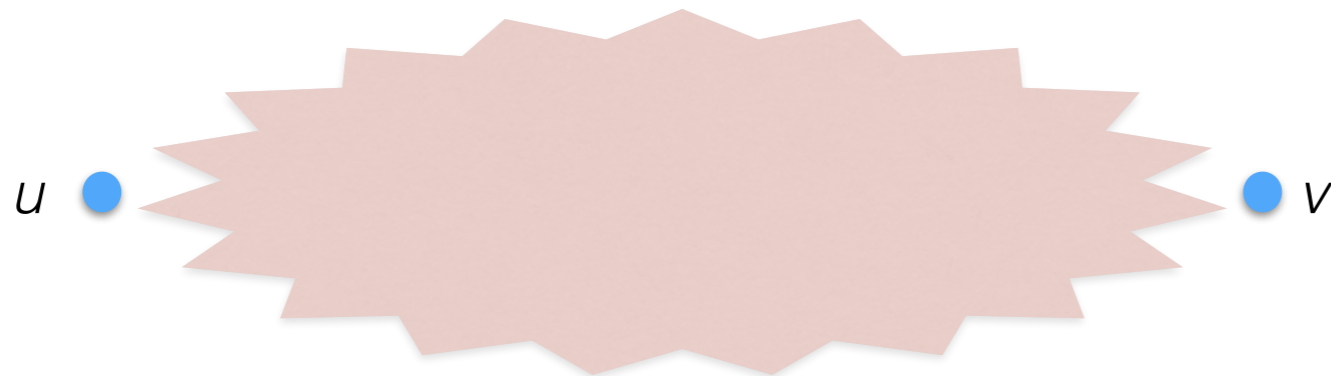
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 - If $w \in N(u,v)$ we win

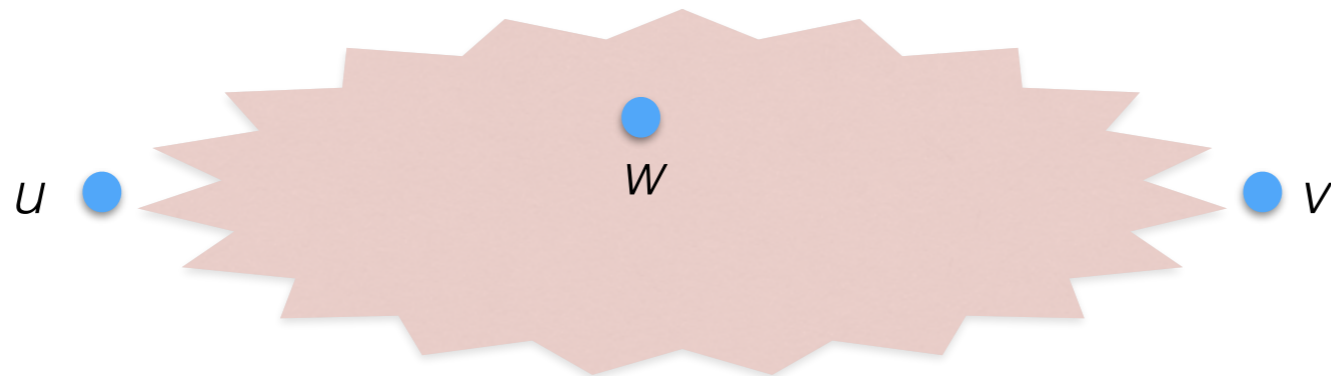
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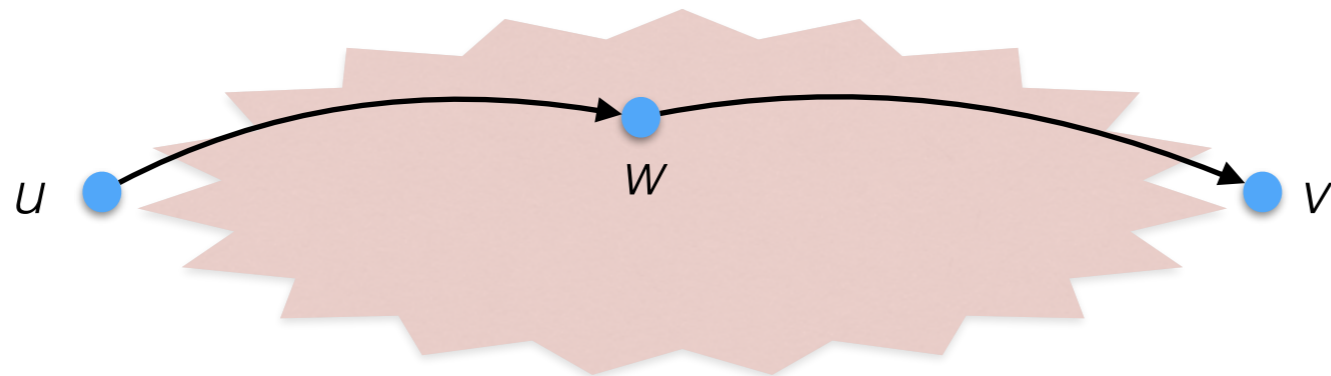
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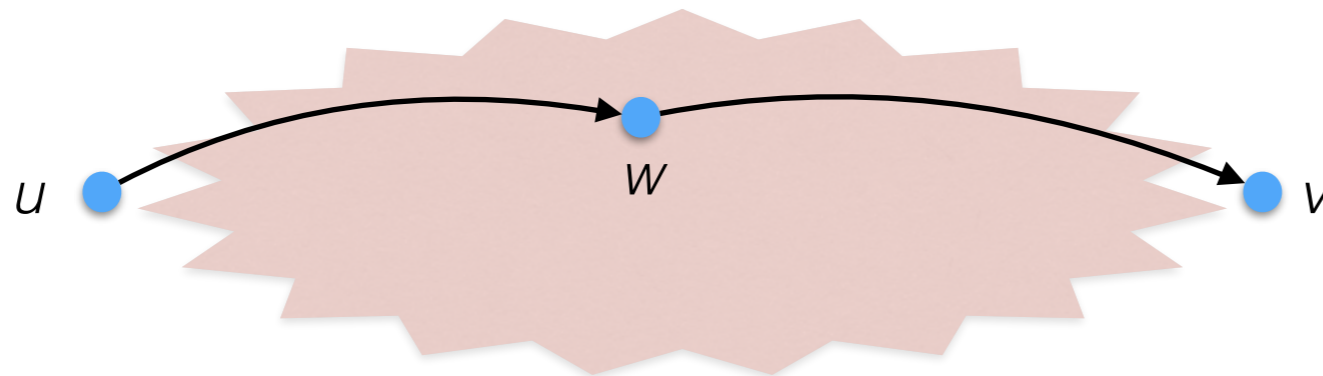
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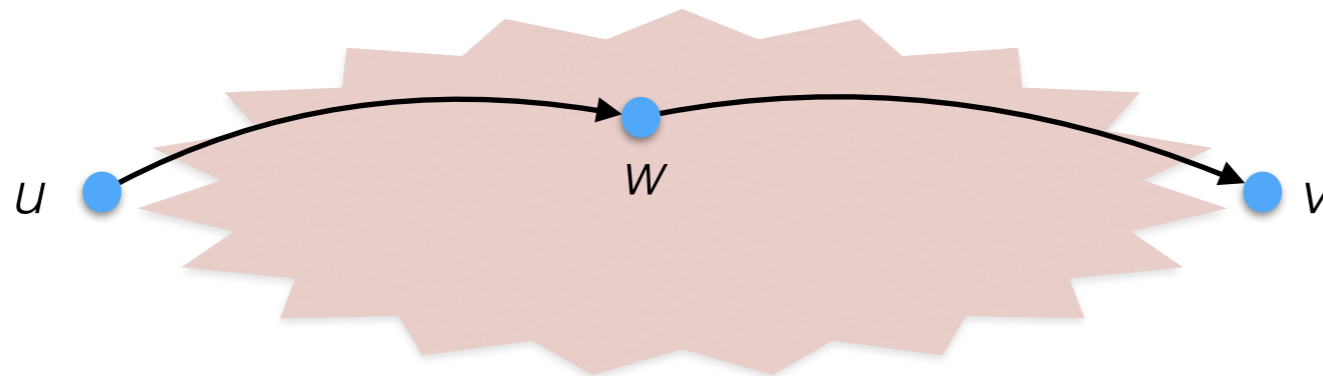
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- If $|N(u,v)| \leq n/\beta$, span (u,v) w.h.p.

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- If $|N(u,v)| \leq n/\beta$, span (u,v) w.h.p.
- Cost at most $\beta * 2n \leq O(\beta * OPT)$

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- Tradeoff between LP rounding and arborescence sampling: rounding for $|N(u,v)| \leq \sqrt{n}$, arborescence sampling for $|N(u,v)| \geq \sqrt{n}$
- $\tilde{O}(n^{1/2})$ -approx

Combined

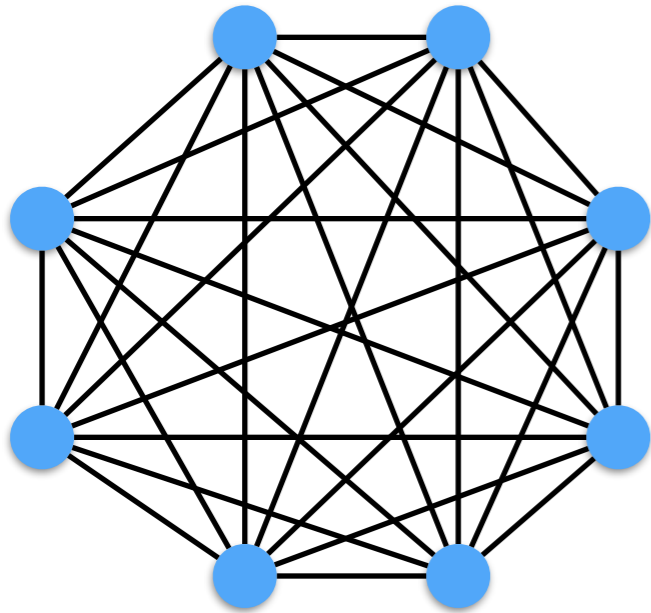
- Tradeoff between LP rounding and arborescence sampling: rounding for $|N(u,v)| \leq \sqrt{n}$, arborescence sampling for $|N(u,v)| \geq \sqrt{n}$
- $\tilde{O}(n^{1/2})$ -approx
- Stretch 3: LP rounding to handle $|N(u,v)| \leq t$ with cost only $O(t^{1/2})$
 - $O(n^{1/2})$ by $t=n$ (without arborescence sampling) [DK '11]
 - $O(n^{1/3})$ with arborescence sampling [BBMRY '11]

Open Questions

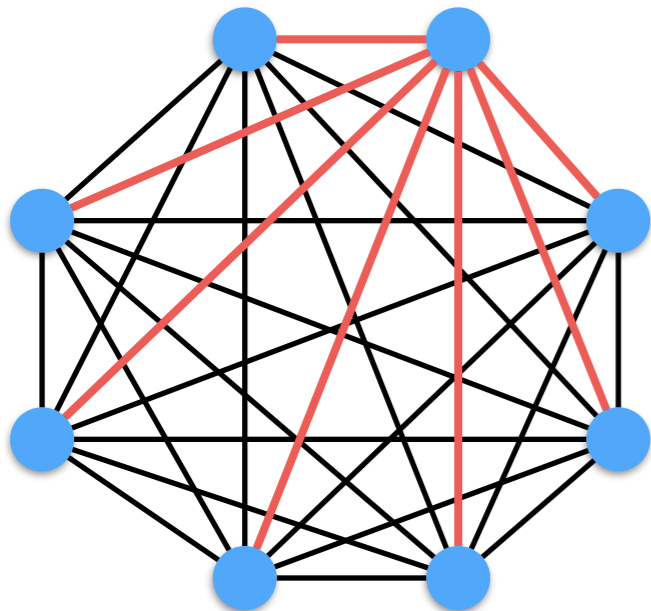
- Improved bounds?
- Arborescence sampling is terrible!
 - Uses a trivial lower bound on OPT
 - Can't handle weights, not as flexible as LP
 - Any way to remove/reduce use of arborescence sampling?
- Back to undirected k -spanner:
 - Directed 3-spanner approx also best for undirected
 - Any way to use LP for larger stretch?

Fault Tolerance

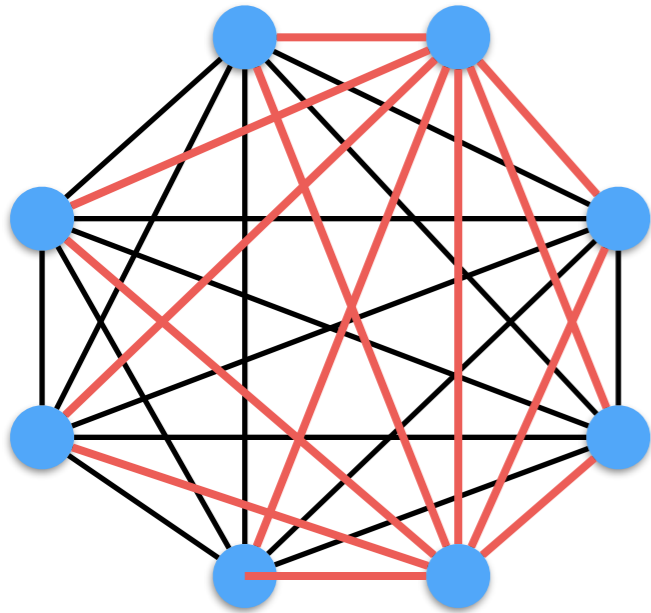
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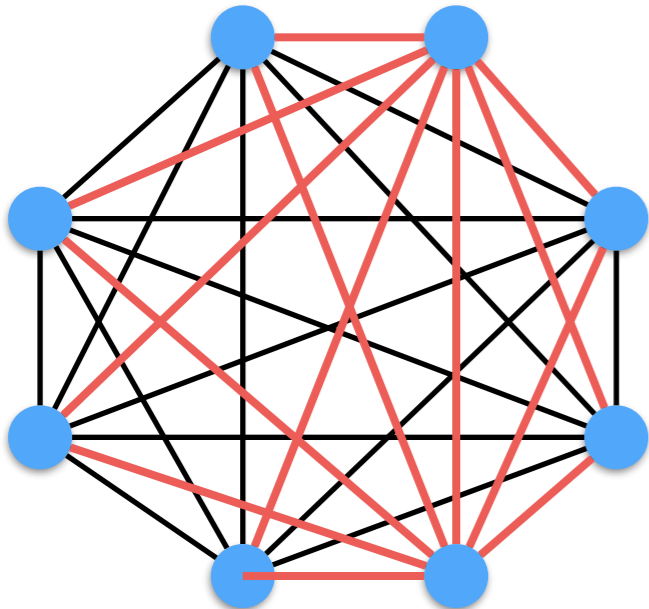


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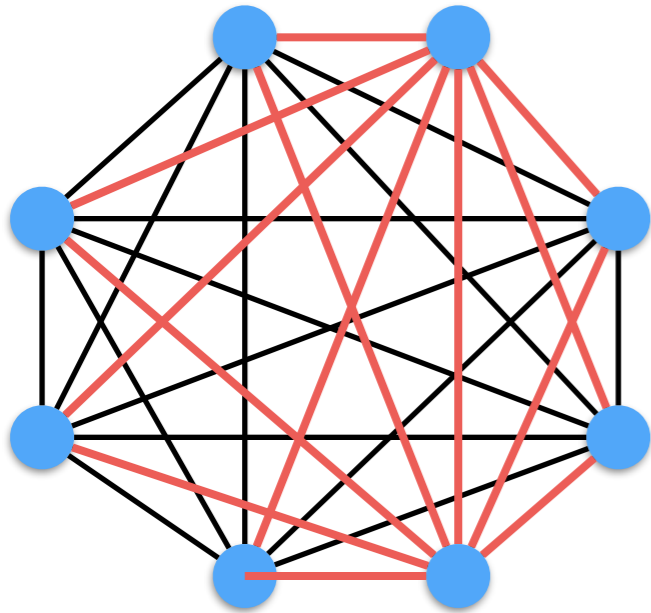


Fault Tolerance

- Def [CLPR STOC'09]: H is an f -fault-tolerant k -spanner if $H - F$ is a k -spanner of $G - F$ for all $F \subseteq V$ with $|F| \leq f$

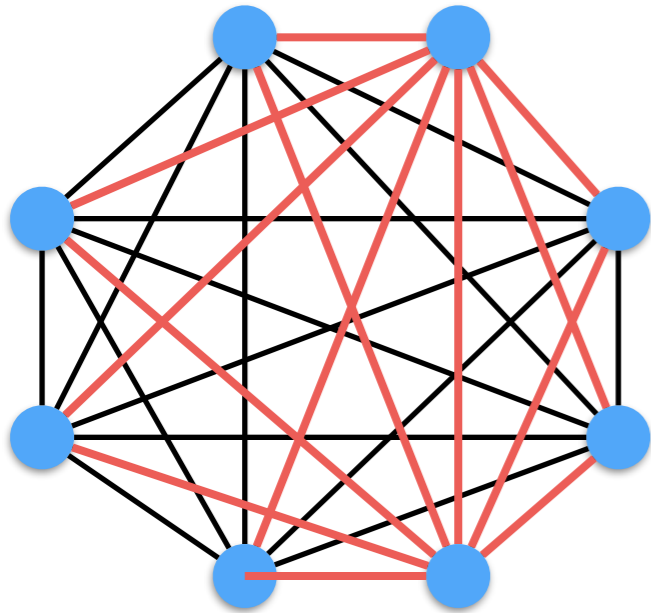


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 - If G a tree, $H = G$ is n -fault tolerant

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 - k -spanner relative to $G - F$, not G
 - If G a tree, $H = G$ is n -fault tolerant
- Reasonable: can't be more fault-tolerant than G

Fault Tolerance: State of the Art

Theorem [D-Krauthgamer PODC'11]:
For every k, f , every graph G admits an f -fault tolerant $(2k-1)$ -spanner with $O(f^2 n^{1+1/k})$ edges

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- Very simple to analyze

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- f -fault tolerant:
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- Both based on rounding LP
- Open Question: approximate f -fault-tolerant k -spanner with no dependence on f ?
 - Tradeoff gives $O(f n^{1/k})$ -approx

Maximum Degree

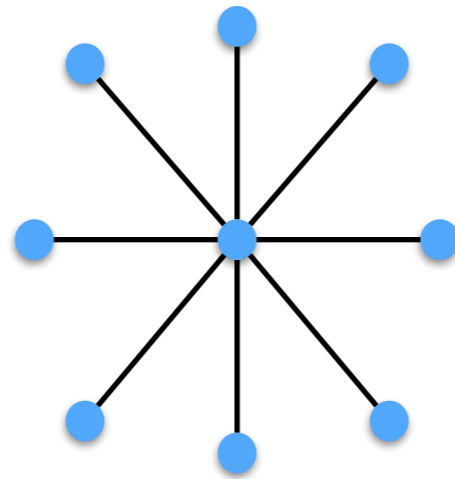
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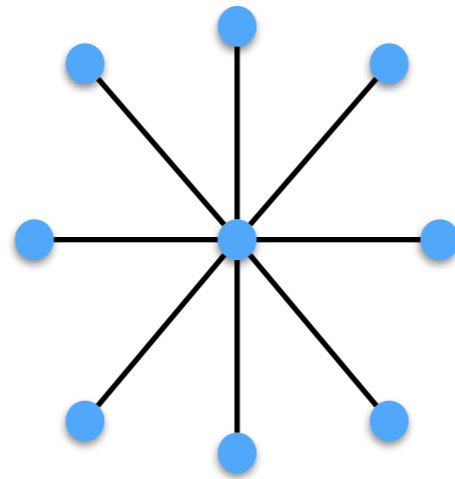
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Maximum Degree

- Max degree instead of number of edges (average degree)

- No tradeoff:



- Lowest Degree k -Spanner (LDkS): find k -spanner that minimizes maximum degree

LDkS vs Basic k -Spanner

- Very different, much more difficult!
- Stretch 2:
 - Basic 2-spanner: $O(\log n)$ -approx [Kortsarz-Peleg TALG'94]
 - LD2S: $O(\Delta^{1/4})$ -approx [Kortsarz-Peleg SICOMP'98]
- Larger stretch:
 - Basic k -Spanner: $O(n^{2/(k+1)})$ -approx
 - LDkS: $\Omega(\log n)$ hardness

LDkS vs Basic k -Spanner

- Very different, much more difficult!
- Stretch 2:
 - Basic 2-spanner: $O(\log n)$ -approx [Kortsarz-Peleg TALG'94]
 - LD2S: $O(\Delta^{1/4})$ -approx [Kortsarz-Peleg SICOMP'98]
- Larger stretch:
 - Basic k -Spanner: $O(n^{2/(k+1)})$ -approx
 - LDkS: $\Omega(\log n)$ hardness

Δ = max degree

Our Results:

- LD2S: $\tilde{O}(\Delta^{3-2\sqrt{2}+\varepsilon}) \approx \tilde{O}(\Delta^{0.172})$ -approx [Chlamtac-D-Krauthgamer FOCS'12]
 - Improvement over $O(\Delta^{1/4})$
- LDkS: $\tilde{O}(\Delta^{(1-1/k)^2})$ -approx, $\Omega(\Delta^{1/k})$ hardness [Chlamtac-D APPROX'14]
 - Improvement over $\Omega(\log n)$ hardness

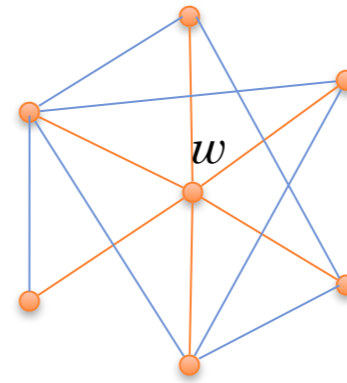
LD2S

LD2S

- Reduce to Smallest m -Edge Subgraph (SmES / min-DkS)

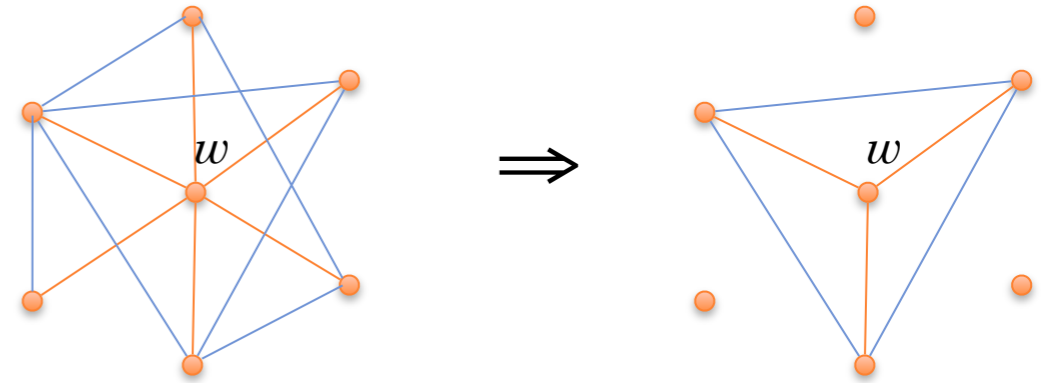
LD2S

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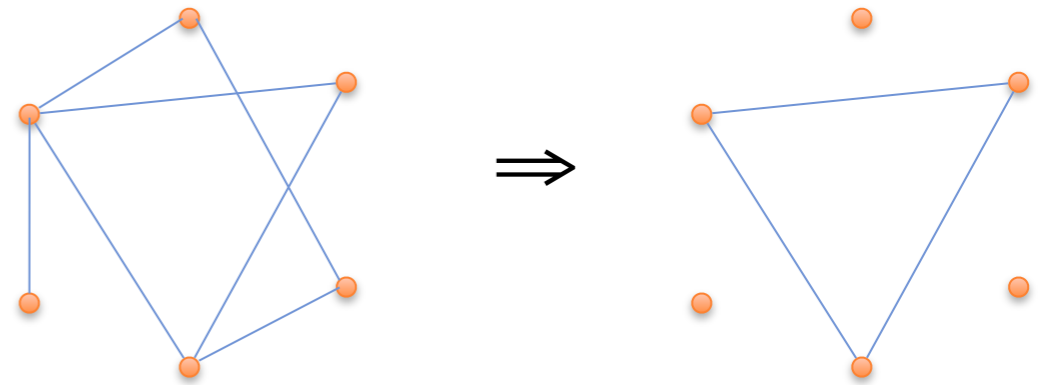
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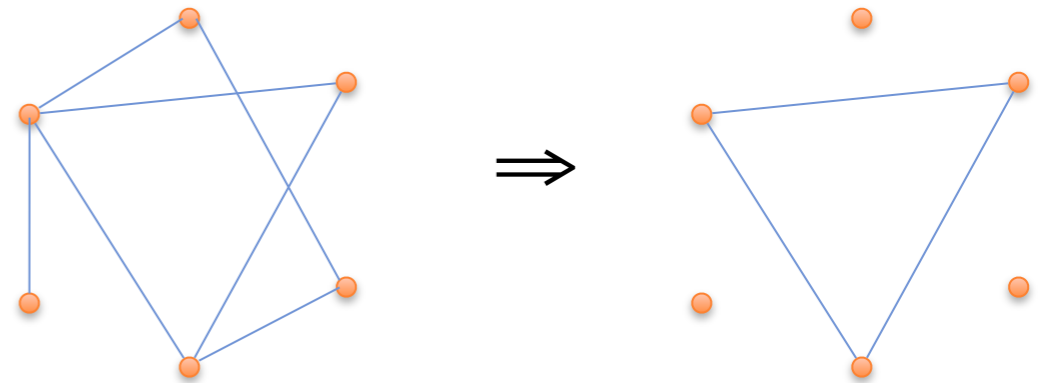
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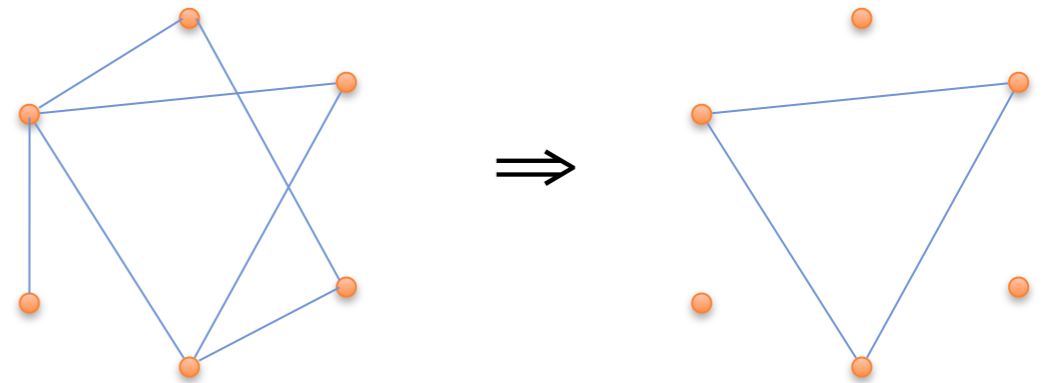
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 - Not black box: LD2S LP contains n SmES LPs
 - Need special “faithful rounding” SmES algorithm



LD2S

- Reduce to Smallest m -Edge Subgraph (SmES / min-DkS)
 - Not black box: LD2S LP contains n SmES LPs
 - Need special “faithful rounding” SmES algorithm
- Improved algorithm for SmES using Sherali-Adams hierarchy
 - $O(n^{1/4})$ directly from DkS
 - SmES used in past, first time improvement over DkS shown



LDkS: Upper Bound

- Straightforward LP:

$$\begin{aligned} \min \quad & d \\ \text{s.t.} \quad & \sum_{(u,v) \in E} x_{(u,v)} \leq d \quad \forall u \in V \\ & \sum_{P \in \mathcal{P}_{u,v}: e \in P} f_P \leq x_e \quad \forall (u,v) \in E, \forall e \in E \\ & \sum_{P \in \mathcal{P}_{u,v}} f_P \geq 1 \quad \forall (u,v) \in E \\ & x_e \geq 0 \quad \forall e \in E \\ & f_P \geq 0 \quad \forall (u,v) \in E, \forall P \in \mathcal{P}_{u,v} \end{aligned}$$

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LDkS: Upper Bound

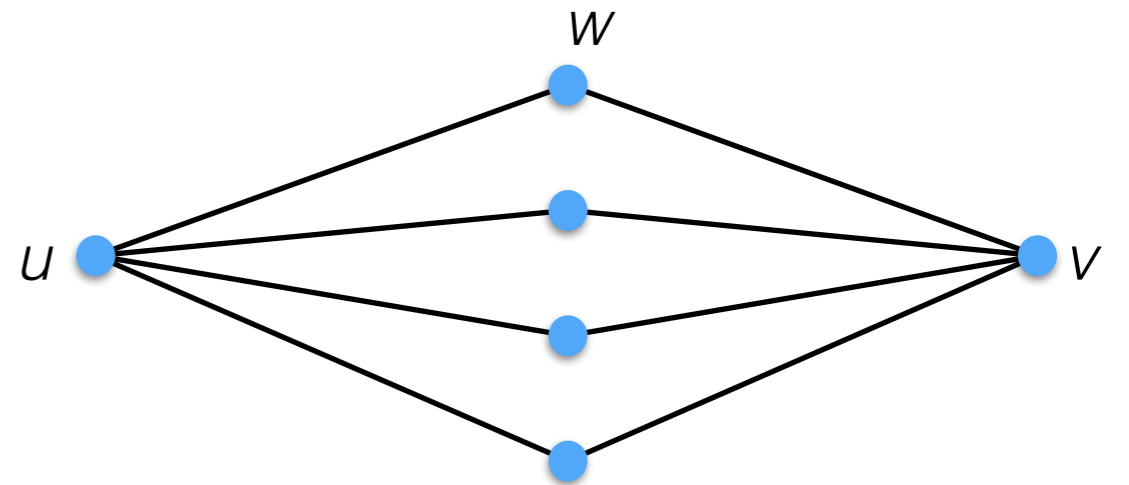
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- Rounding: include e with probability $x_e^{1/k}$
- Not hard to analyze cost: trick is proving rounded solution is a k -spanner

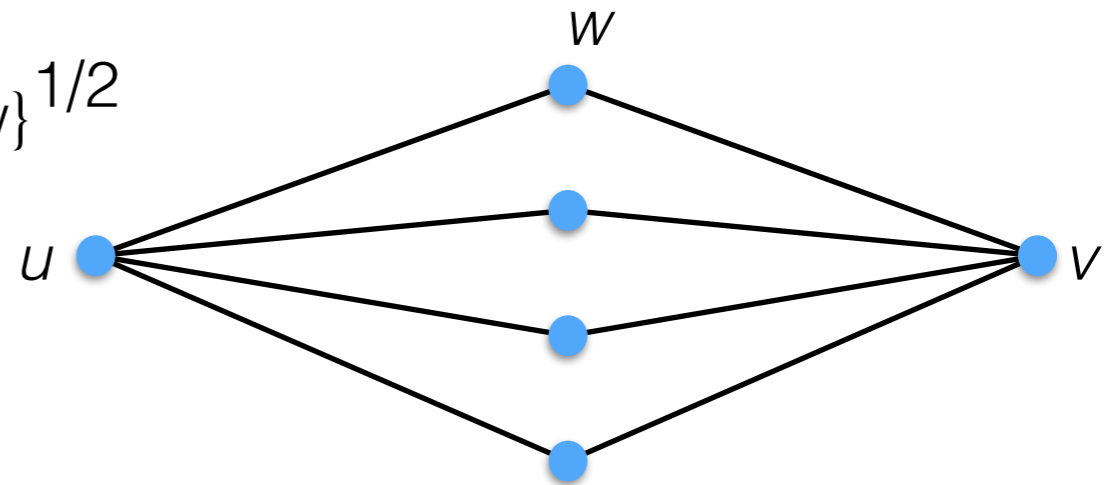
LDkS: Upper Bound (II)

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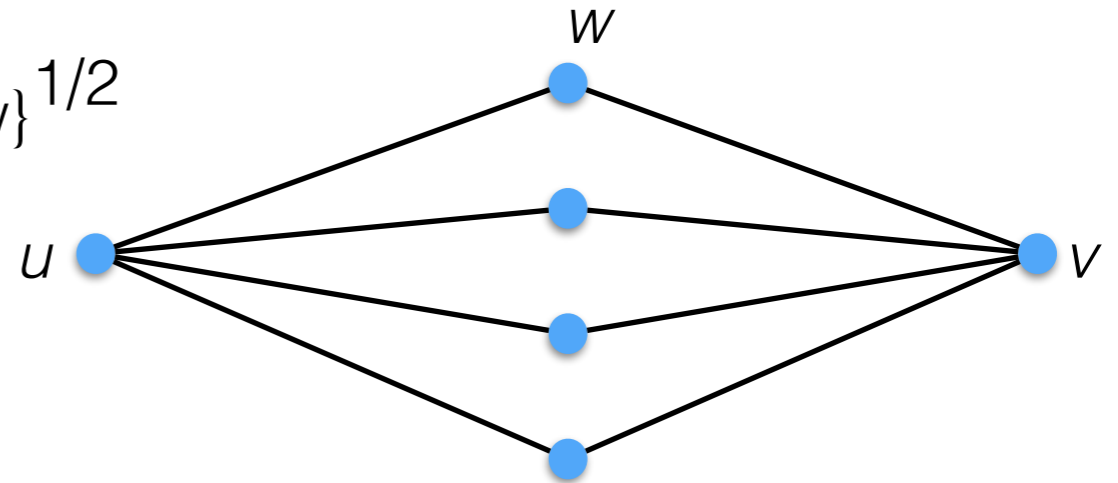
LDkS: Upper Bound (II)

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 $\geq f(u,w,v)$



LDkS: Upper Bound (II)

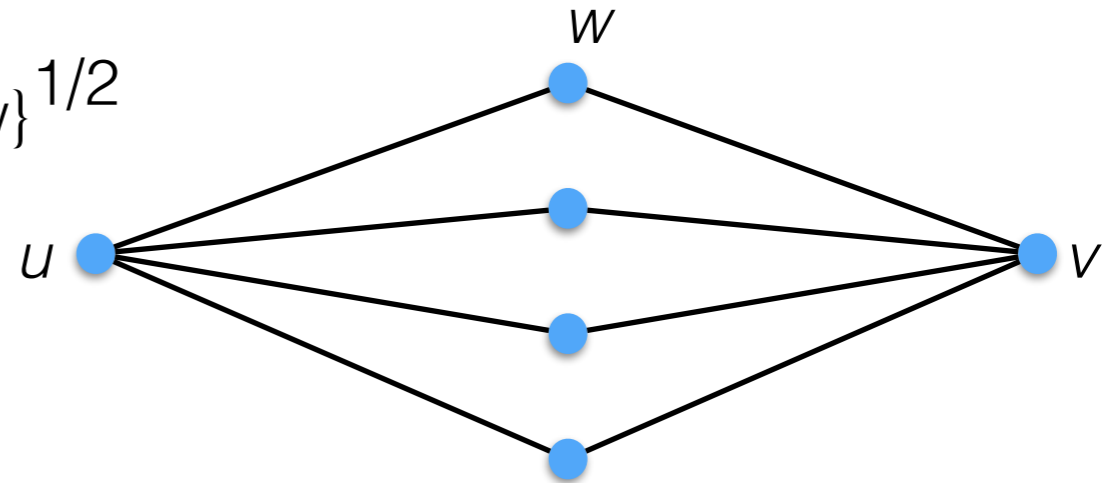
- $\Pr[\text{get } u-w-v] = X_{\{u,w\}}^{1/2} X_{\{v,w\}}^{1/2}$
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LDkS: Upper Bound (II)

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- If paths disjoint, get each path independently so $\Pr[\text{span } u-v] \geq 1 - \prod_w (1 - f_{(u,w,v)}) \geq 1 - 1/e$
- But for stretch > 2 paths not disjoint
 - Complicated bucketing of paths to argue lots of flow must be on nearly-disjoint paths

LDkS: Lower Bound

- Based on lower bound for Basic k -Spanner
 - Interlacing of sampling with reduction
 - Start with hard Label Cover instance, subsample edges, apply reduction, subsample edges
- Need girth of Label Cover graph and reduction graph to be larger than k
 - Leads to hardness that gets worse with k

LDkS: Open Question

- What is the right approximation?
- Upper bound $\tilde{O}(\Delta^{(1-1/k)^2})$ gets larger with k , lower bound $\Omega(\Delta^{1/k})$ gets smaller with k

Conclusion

- Tons of work on graph spanners, very little on optimizing/approximating spanners
- We know a fair amount, but still many very basic open questions
 - Beating trivial bound from tradeoff for basic k -spanner?
 - Is any dependence on f necessary for approximating fault-tolerant spanners?
 - Does Lowest Degree k -Spanner get easier or harder as k increases?
 - Approximating weight?
 - Approximating geometric spanners?

Thanks!

(Work on spanners with me!)